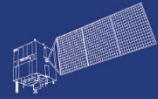


HY



HJ-1AB



CBERS



Gaofen



Beijing-2



Sentinel-1



Sentinel-2



Sentinel-3



Sentinel-5p



Aeolus

2023 DRAGON 5 SYMPOSIUM
3rd YEAR RESULTS REPORTING
11-15 SEPTEMBER 2023

PROJECT ID. 58070

**CALIBRATION AND VALIDATION OF THE
FIRST CHINESE GNSS-R MISSION—
BUFENG-1 A/B**

DATE: WEDNESDAY, 13/SEP/2023

ID. 58070

PROJECT TITLE: CALIBRATION AND VALIDATION OF THE FIRST CHINESE GNSS-R MISSION—BUFENG-1 A/B

PRINCIPAL INVESTIGATORS: CHENG JING, LI WEIQIANG

CO-AUTHORS: WEI WAN, FENG LU, XINLIANG NIU, XIUWAN CHEN, ANTONIO RIUS, ESTEL CARDELLACH, SERNI RIBÓ, BAOJIAN LIU, ZHIZHOU GUO, YANG NAN

PRESENTED BY: CHENG JING

Objectives

- Collocation of integrated ESA-CHINA EO data products and BuFeng-1 data preprocessing
- Calibration of the BuFeng-1 A/B main observables, including NBRCS, power DDM, and SNR
- Validation of the calibrated results from BuFeng-1 A/B;
- Optimization and improvements of future spaceborne GNSS-R instruments

Details of data utilization

- ESA EO data: SMOS (MIRAS), Sentinel-3 (SIRAL)
- CHINA EO data: FY Series (MWRI), CFOSAT (SCAT), HY-1&2 (COCTS), BF-1 A/B (GNSS-R)
- Meteorological reanalysis data: ECMWF ERA-5, CMA CRA
- In-situ data: ISMN sites
- Others: SMAP, DTU MSS

Data access (list all missions and issues if any). NB. in the tables please insert cumulative figures (since July 2020) for no. of scenes of high bit rate data (e.g. S1 100 scenes). If data delivery is low bit rate by ftp, insert “ftp”

ESA /Copernicus Missions	No. Scenes	ESA Third Party Missions	No. Scenes	Chinese EO data	No. Scenes
1. SMOS (MIRAS)		1. ECMWF ERA-5		1. FY Series (MWRI)	
2. Sentinel-3 (SRAL)		2. CMA CRA		2. CFOSAT (SCAT)	
3.		3. ISMN sites		3. HY-1&2 (COCTS)	
4.		4. SMAP		4. BF-1 A/B (GNSS-R)	
5.		5. DTU MSS		5.	
Total:		Total:		Total:	
Issues:		Issues:		Issues:	

Chinese BF-1 Mission

Launch date: June 5th, 2019

Frequency: GPS L1 & BeiDou B1

Antenna gain: 14 dBi

Mass: 10 kg

Power consumption: 30 W

Specular Points: 4/s



Sea platform launch



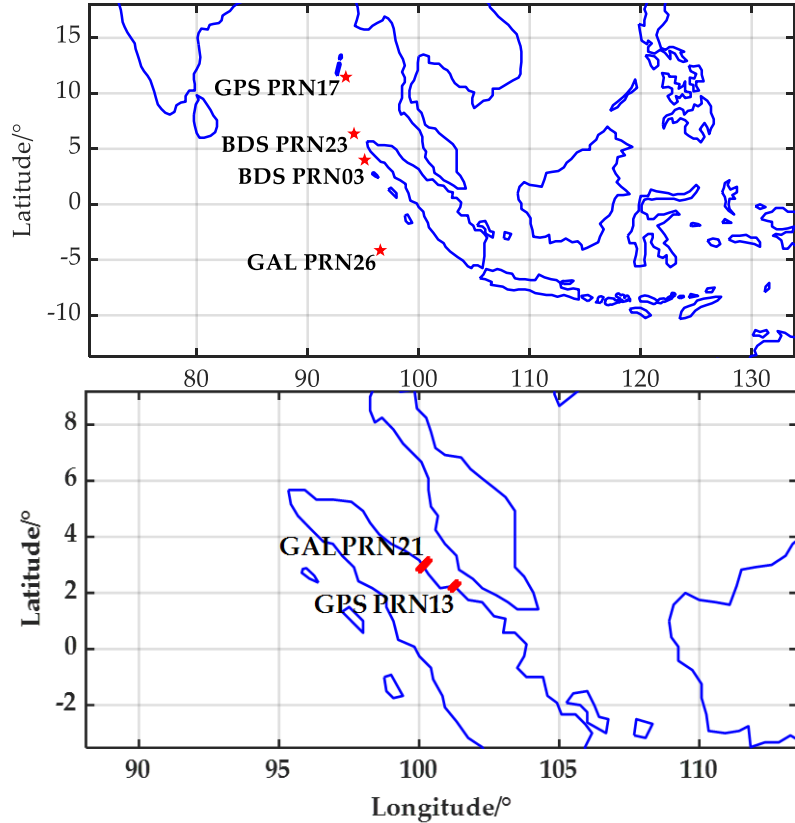
**GNSS-R
Instruments**

GNSS-R receiver	
Frequency	GPS L1 and BDS B1
Antenna Gain	≥14 dBi
Mass	≤10 kg
Power Consumption	≤30 W
DDM Mode	
Delay Chip Resolution	1/4 chip
Doppler Frequency Resolution	500 Hz
Specular Points	4 from both sides of the twin SVs
Raw Data Mode	
L1CA Sampling Rate	4.092 MHz
B1I Sampling Rate	8.184 MHz
Duration	12 sec per pass

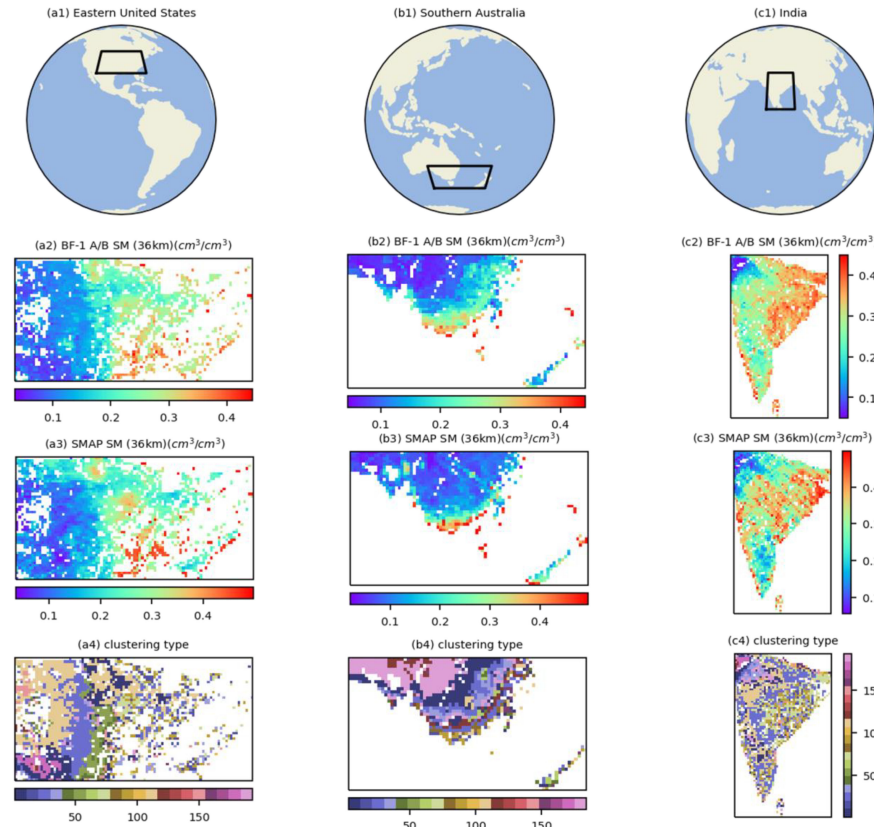
BF-1 Data availability statement

As the first Chinese spaceborne GNSS-R mission, BF-1 is a technical demonstration satellite mission. Under the Dragon 5 project framework, BF-1 data have been distributed among the participating members. In July of 2023, The 4th anniversary meeting of BF-1 mission has been taken place in Beijing and made a data sharing plan arranged by CMA and CASC. The information is scheduled to be public to the GNSS-R community. BF-1 products now are available to the GNSS-R science community from the corresponding author, Feng Lu, upon reasonable request.

Correspondence: lufeng@cma.gov.cn



Raw IF data Study Areas



In-land Soil Moisture Areas

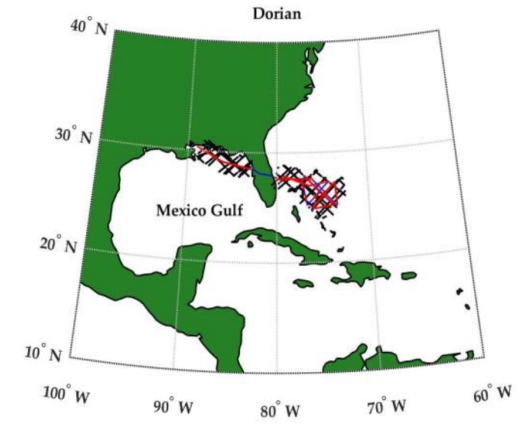


Table 1. NOAA Hurricane Season Data 2019

Name	Date	Volume
Barry	7/11-7/23	9
Dorian	8/26-9/6	35
Humberto	9/13-9/19	10
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Jerry	9/19-9/24	12
Karen	9/22-9/26	7
Lorena	9/19-9/21	3
Lorenzo	9/28-9/29	2

Hurricane Observation Area

the results after 3 years of activity
BF-1 Sea Surface Height Measurement

Sea Surface Height Measurements

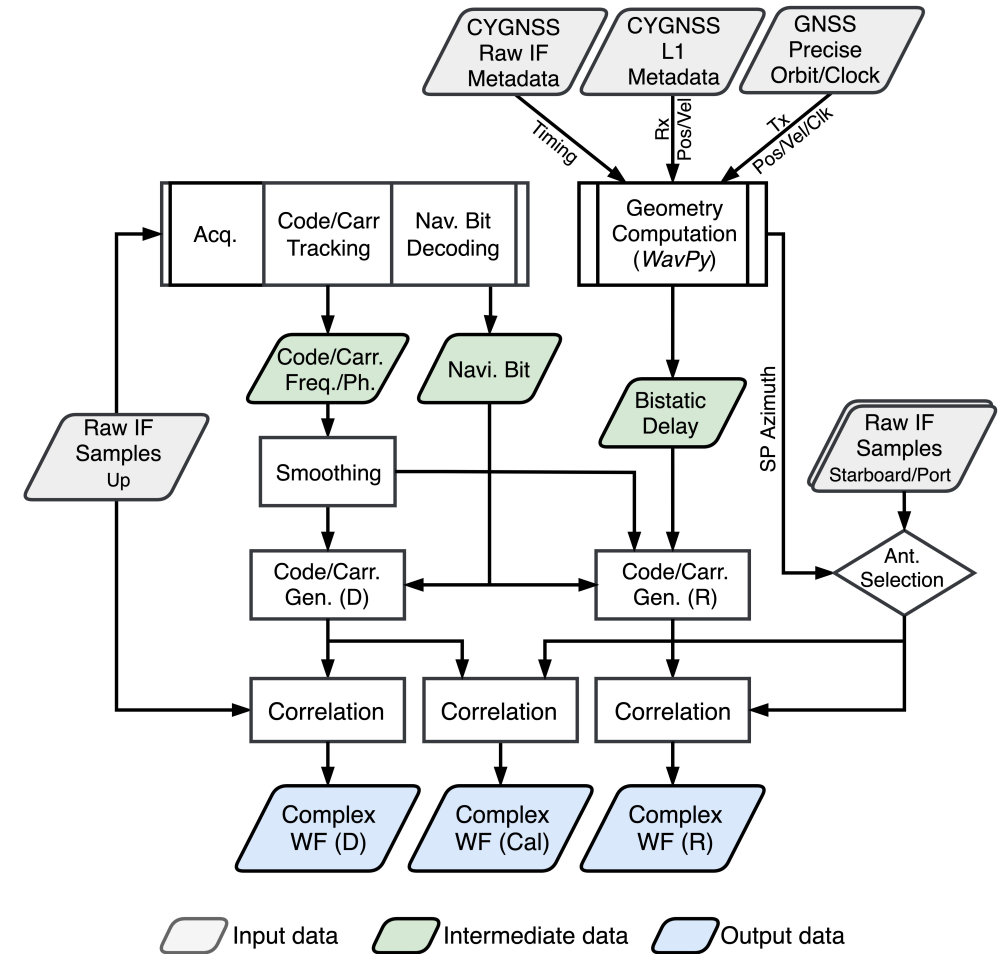
- Data Latency: diagnostic mode will start the raw IF data collecting about 12 seconds within every pass
- Data Time: the year of 2020
- Frequency: GPS L1, BDS B1, GAL E1
- Channels: 1 direct, 2 reflections
- Auxiliary data: IGS, ECMWF reanalysis, DTU MSS

BF-1 Spaceborne GNSS-R Raw IF data of 2020

Date	Start Time	Resource	Code	Mode
2020/2/12	17:42:17	GPS PRN17	L1 C/A	Group Delay
2020/2/13	16:02:22	BDS PRN23	B1C	Group Delay
2020/2/16	16:04:26	BDS PRN03	B1I	Group Delay
2020/2/23	12:47:58	GAL PRN26	E1	Group Delay
2020/2/13	16:02:22	GAL PRN21	/	Carrier Phase
2020/8/23	21:07:00	GPS PRN13	/	Carrier Phase

Sea Surface Height Measurements

- Close-loop processing of the direct signal
- Open-loop (OP) processing of the reflected delay-waveforms
- Ancillary information: the positions, velocities, and timing information of the GNSS transmitters and BF-1 satellites
- Corrections: ionospheric delay, tropospheric delay, and the tidal corrections.



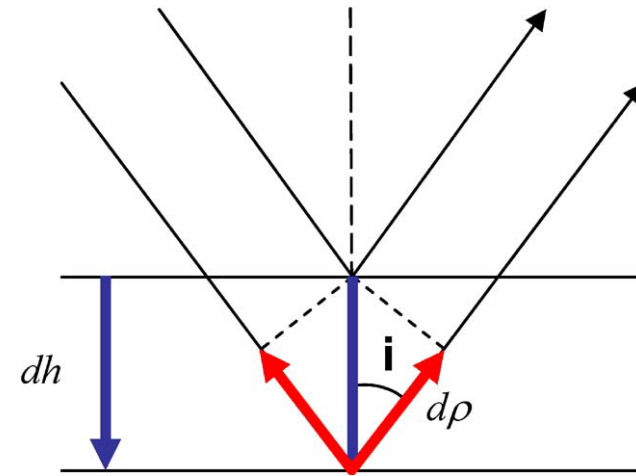
Li, W., et al. (2018). "Revisiting the GNSS-R waveform statistics and its impact on altimetric retrievals." *IEEE Transactions on Geoscience and Remote Sensing* **56(5): 2854-2871**.

Li, W., et al. (2019). "Assessment of spaceborne GNSS-R ocean altimetry performance using CYGNSS mission raw data." *IEEE Transactions on Geoscience and Remote Sensing* **58(1): 238-250**.

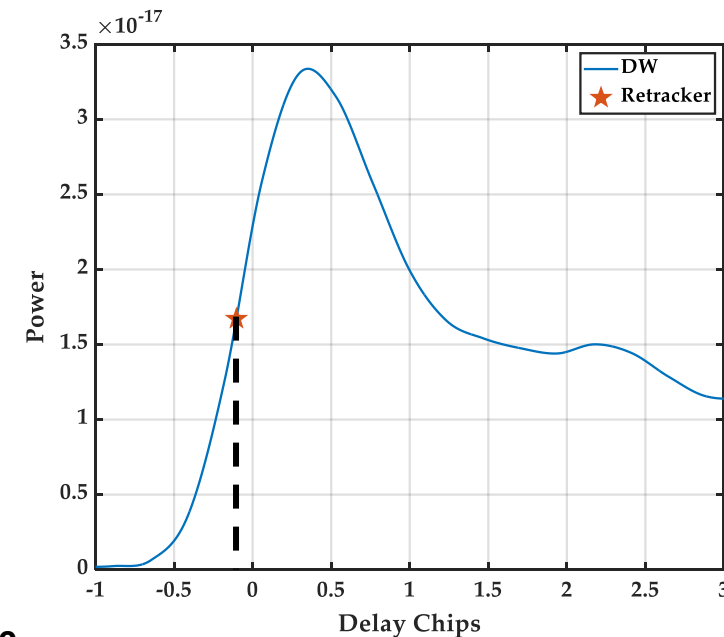
Sea Surface Height Measurements

Group Delay

- Signal path: delay between paths
- Specular point positions recalculation
- Retracker: DER, HALF, and FIT
- Corrections: ionospheric and tropospheric delays, tides, dynamic bar, etc.



Path delays



Wave retracker

Li, W., et al. (2018). "Revisiting the GNSS-R waveform statistics and its impact on altimetric retrievals." *IEEE Transactions on Geoscience and Remote Sensing* **56(5): 2854-2871**.

Li, W., et al. (2019). "Assessment of spaceborne GNSS-R ocean altimetry performance using CYGNSS mission raw data." *IEEE Transactions on Geoscience and Remote Sensing* **58(1): 238-250**.

Sea Surface Height Measurements - Group Delay Results

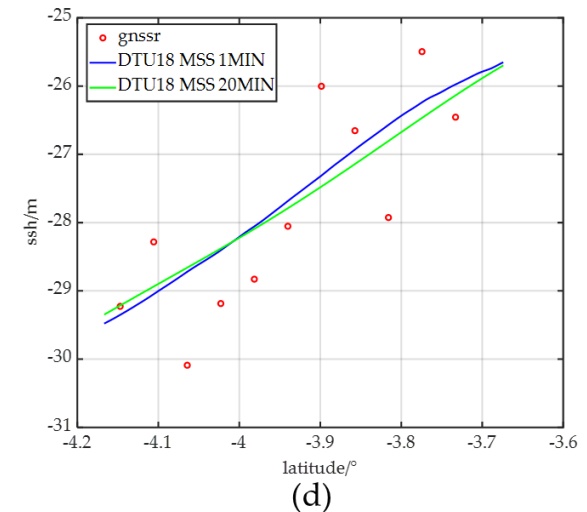
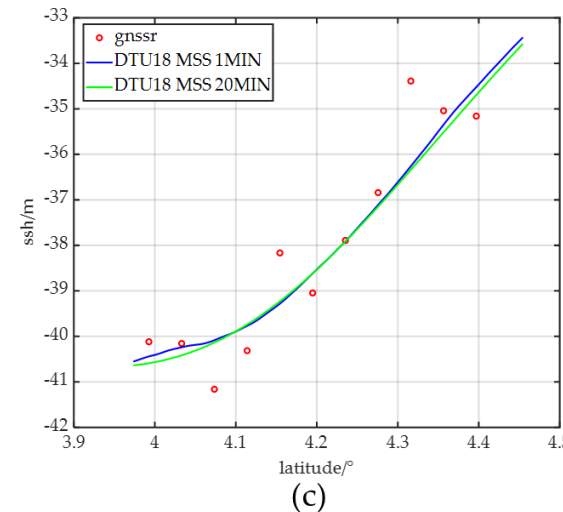
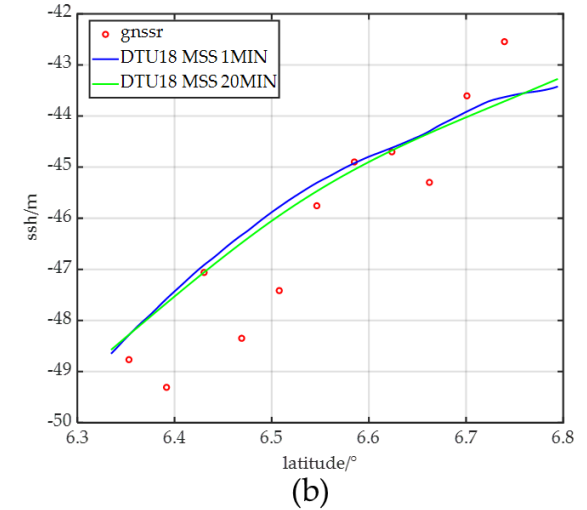
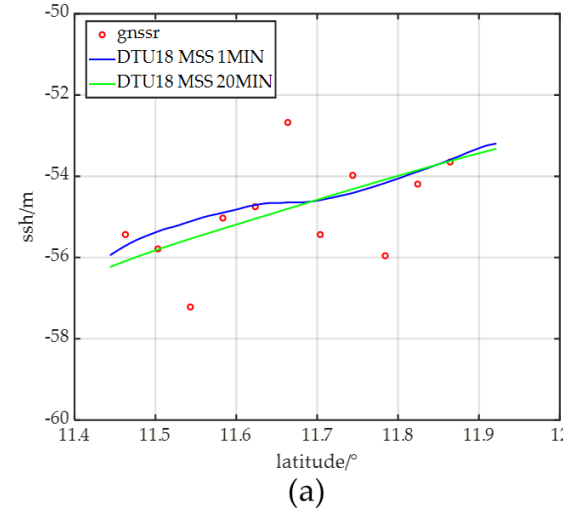
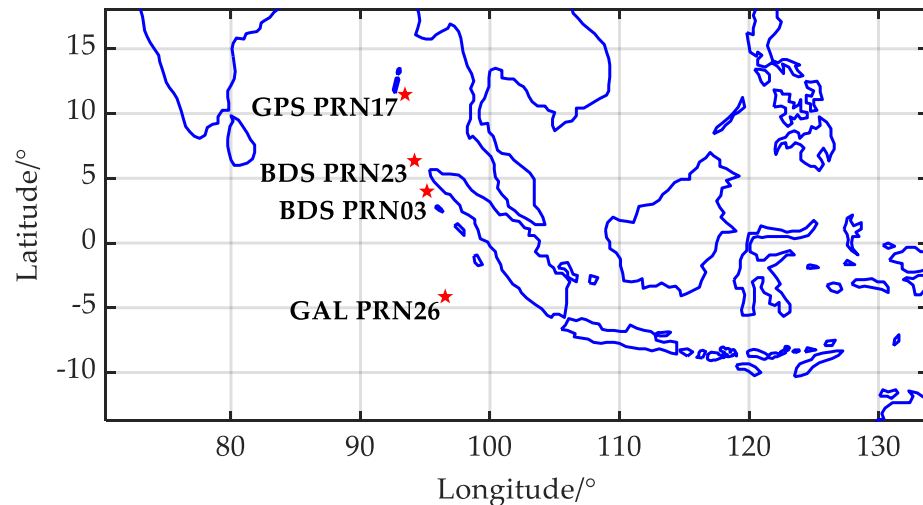
- Four specular points with 11-sec latency
- Resolution: ~3.3-MIN (1 Hz)
- Validation: DTU MSS 1-MIN & 20-MIN

(a) GPS PRN17: RMSD of 1.06 m

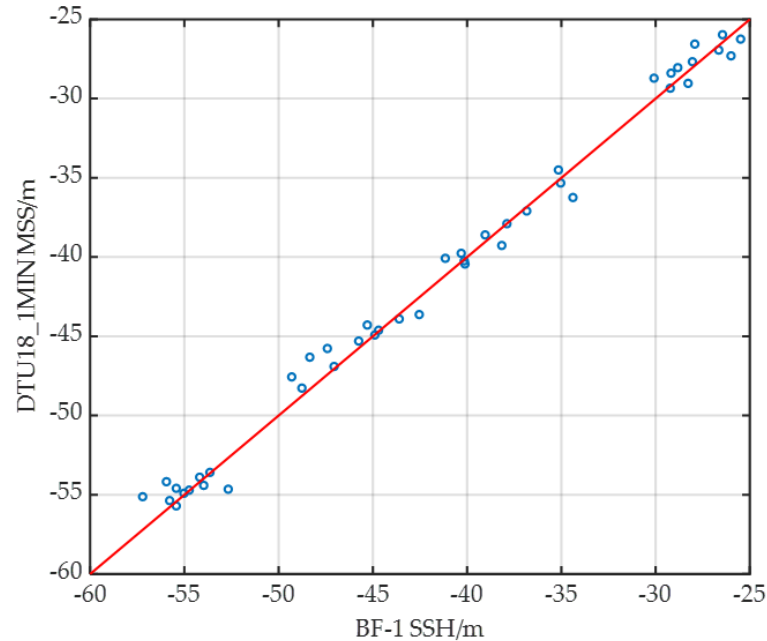
(b) BDS PRN23: RMSD of 1.01 m

(c) BDS PRN03: RMSD of 0.81 m

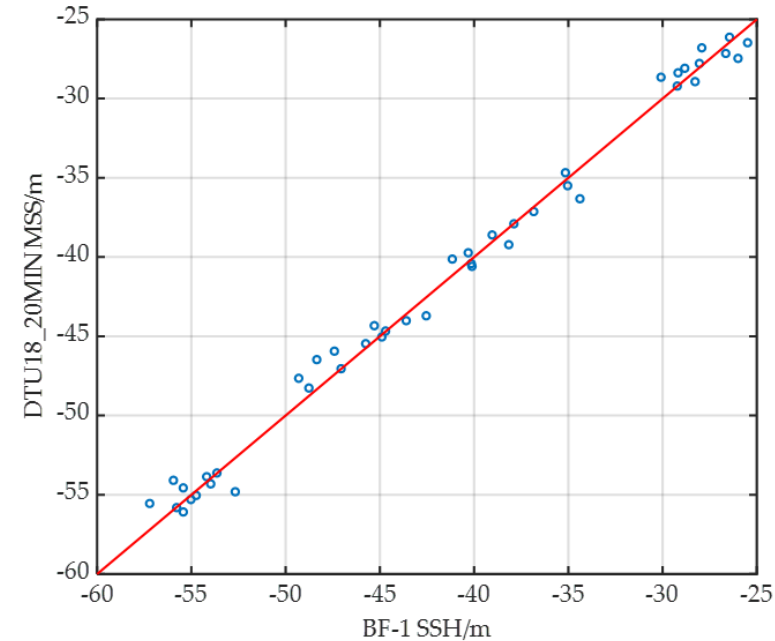
(d) Galileo PRN26: RMSD of 0.86 m.



Sea Surface Height Measurements - Group Delay Results



(a)



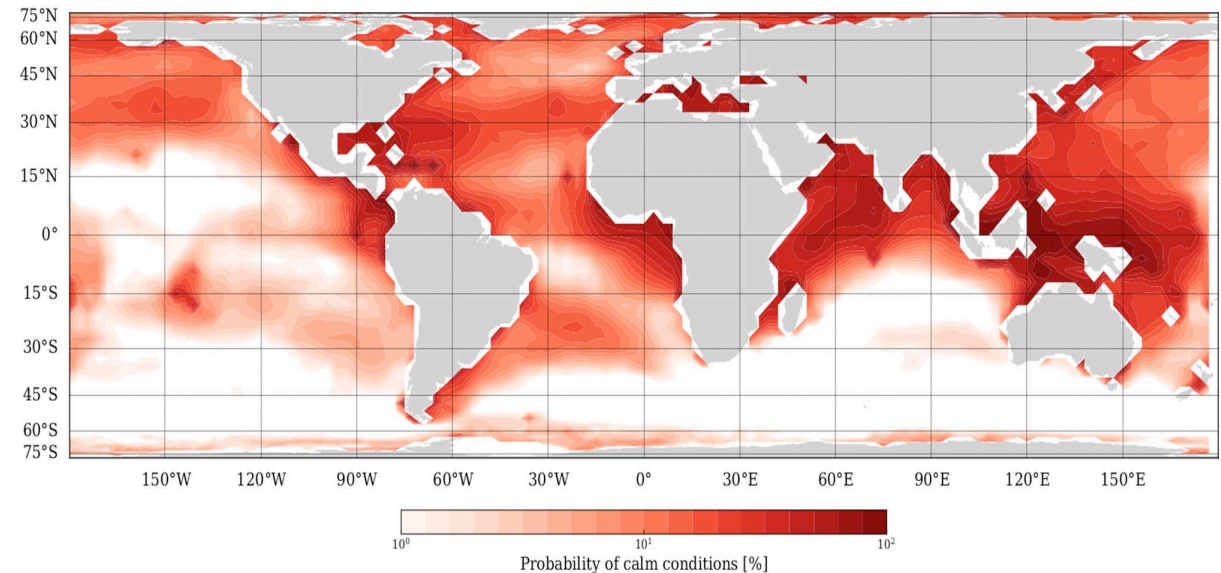
(b)

(a) results compared with DTU18 1-min mean sea surface measurements. The total RMSD is 0.93 m with the R^2 of 99.17%. (b) results compared with DTU18 20-min products. The parameters of RMSD and R^2 are 0.94 m and 99.15%, respectively.

Sea Surface Height Measurements

Carrier Phase

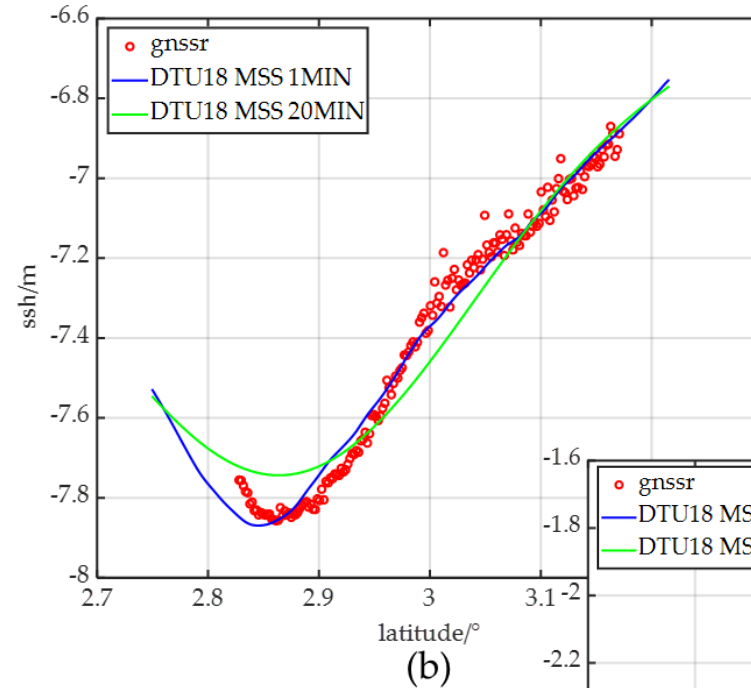
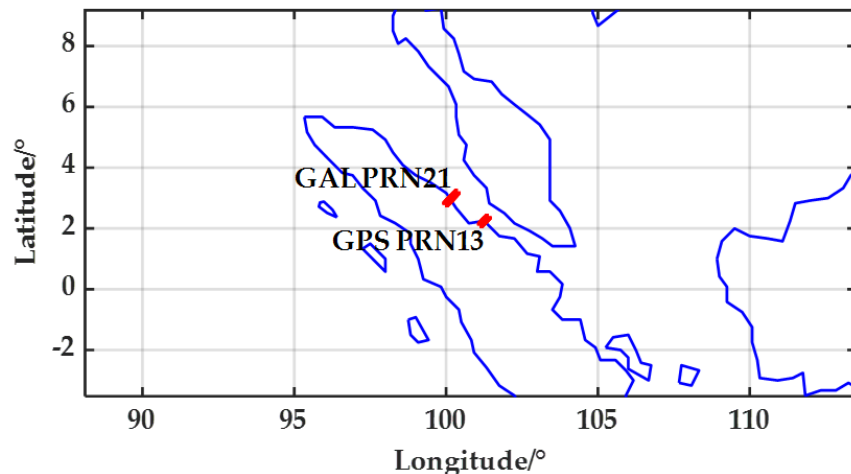
- BF-1 raw IF data with the GA feature are abstracted to track and measure the sea level
- Global map of calm condition of high probability
- High spatial resolution of 20 Hz but low coverage
- No high gain antenna needed



**Global Map of Sea
Calm Condition**

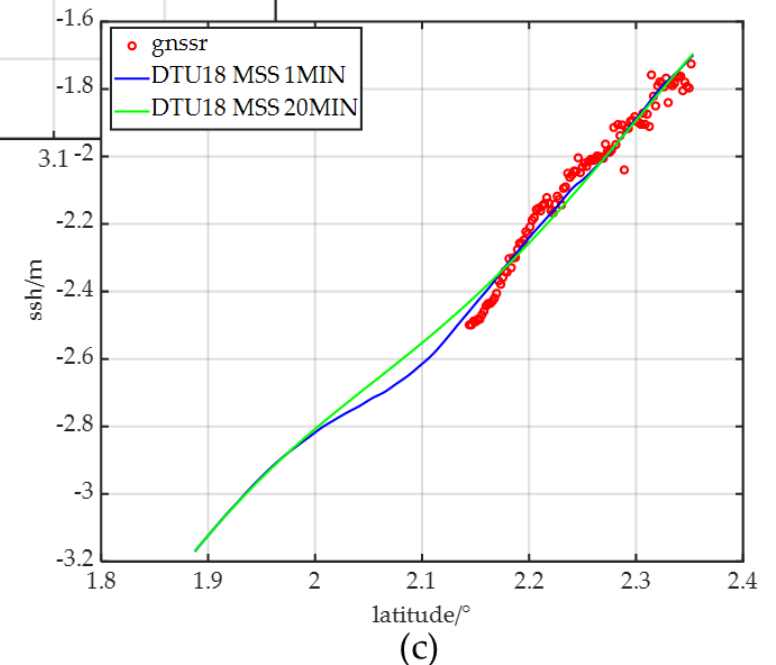
Sea Surface Height Measurements - Carrier Phase Results

- BF-1 raw IF data with the GA feature
- Signal: Galileo PRN21, GPS PRN13
- Validation: DTU MSS 1-MIN & 20-MIN
- Area: calm sea surface roughness
- Resolution: ~0.16-MIN (20 Hz)
- Accuracy: 6.65 cm vs DTU MSS 1-MIN
4.04 cm vs DTU MSS 20-MIN



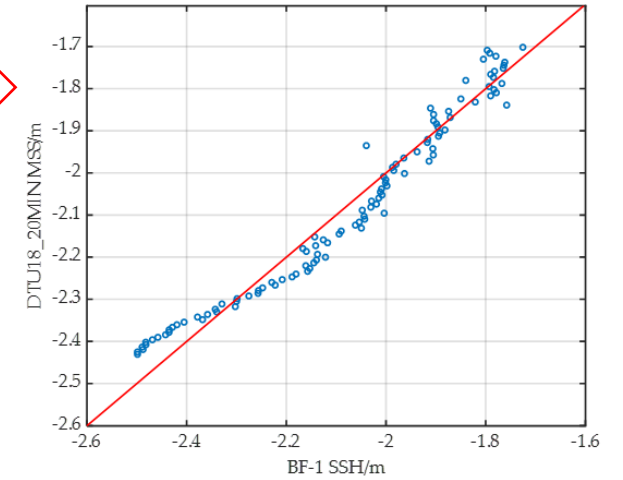
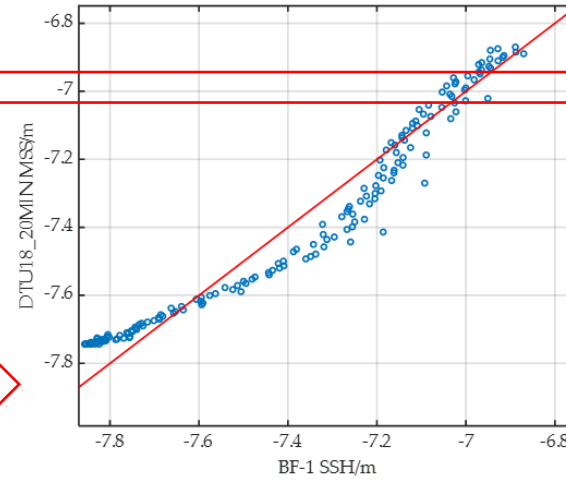
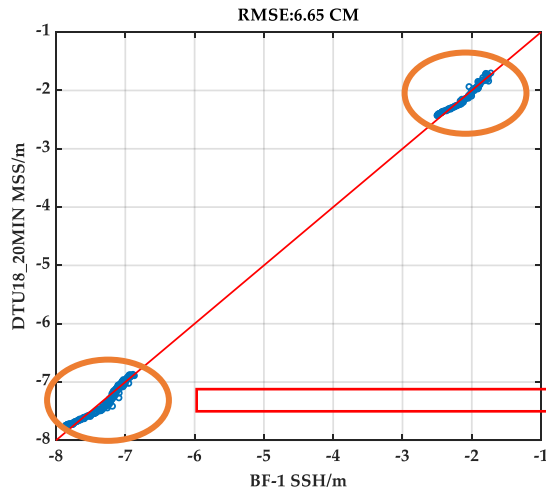
Galileo PRN21

GPS PRN13

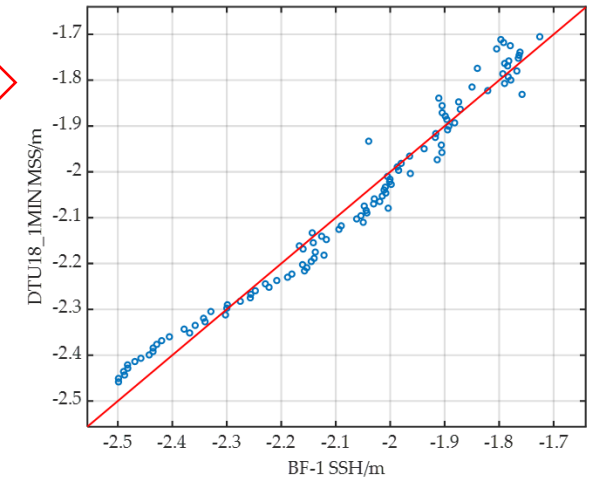
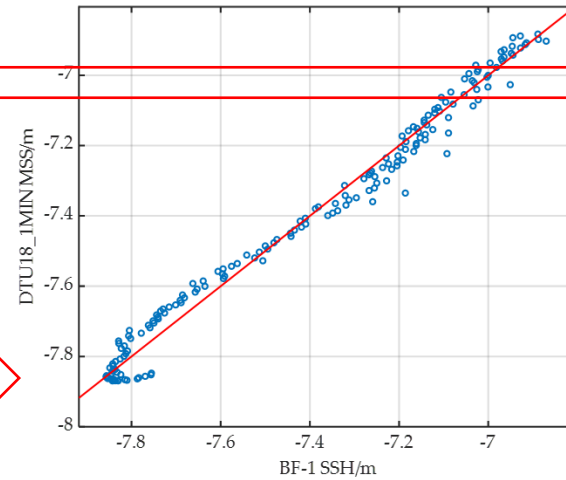
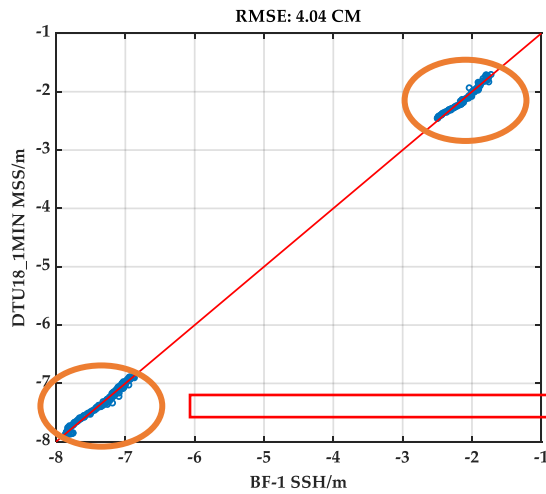


Sea Surface Height Measurements - Carrier Phase Results

**20-MIN RES.
RMSE=6.65 CM**



**1-MIN RES.
RMSE=4.04 CM**

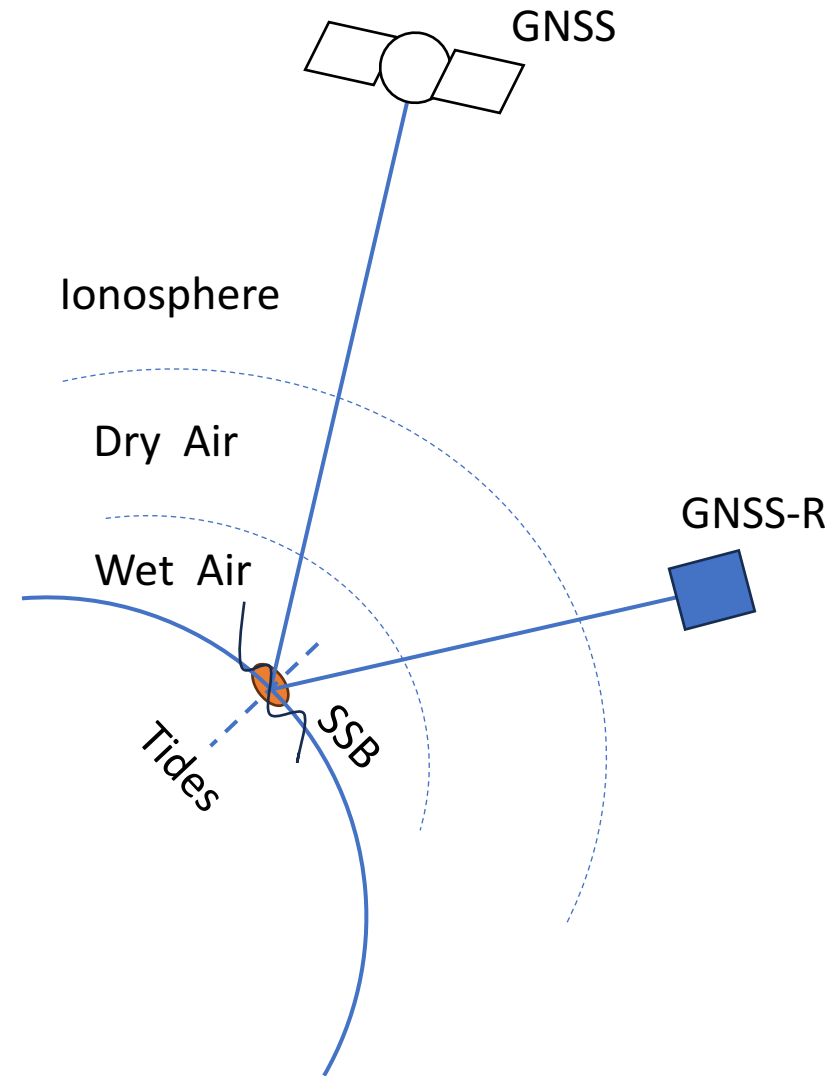


Galileo PRN21

GPS PRN13

Sea Surface Height Measurements - Corrections

- GNSS-R SSH corrections
- Similar with the radar altimeter
 - GNSS-R related biases (above the water):
 - Ionosphere: L-band dual-frequency
 - Sea state bias: waveform derived sea surface roughness
 - Slant delays of Dry atmosphere and wet atmosphere.
 - Sea surface corrections: Dynamic Inversive Bar (DIB), Pole tide, sea tide, and solid tide.



Sea Surface Height Measurements - Corrections

- Validation data: Sentinel-3 (SRAL)

Troposphere: Saastamoinen & ECMWF

Sea Tide Correction: EXPO9

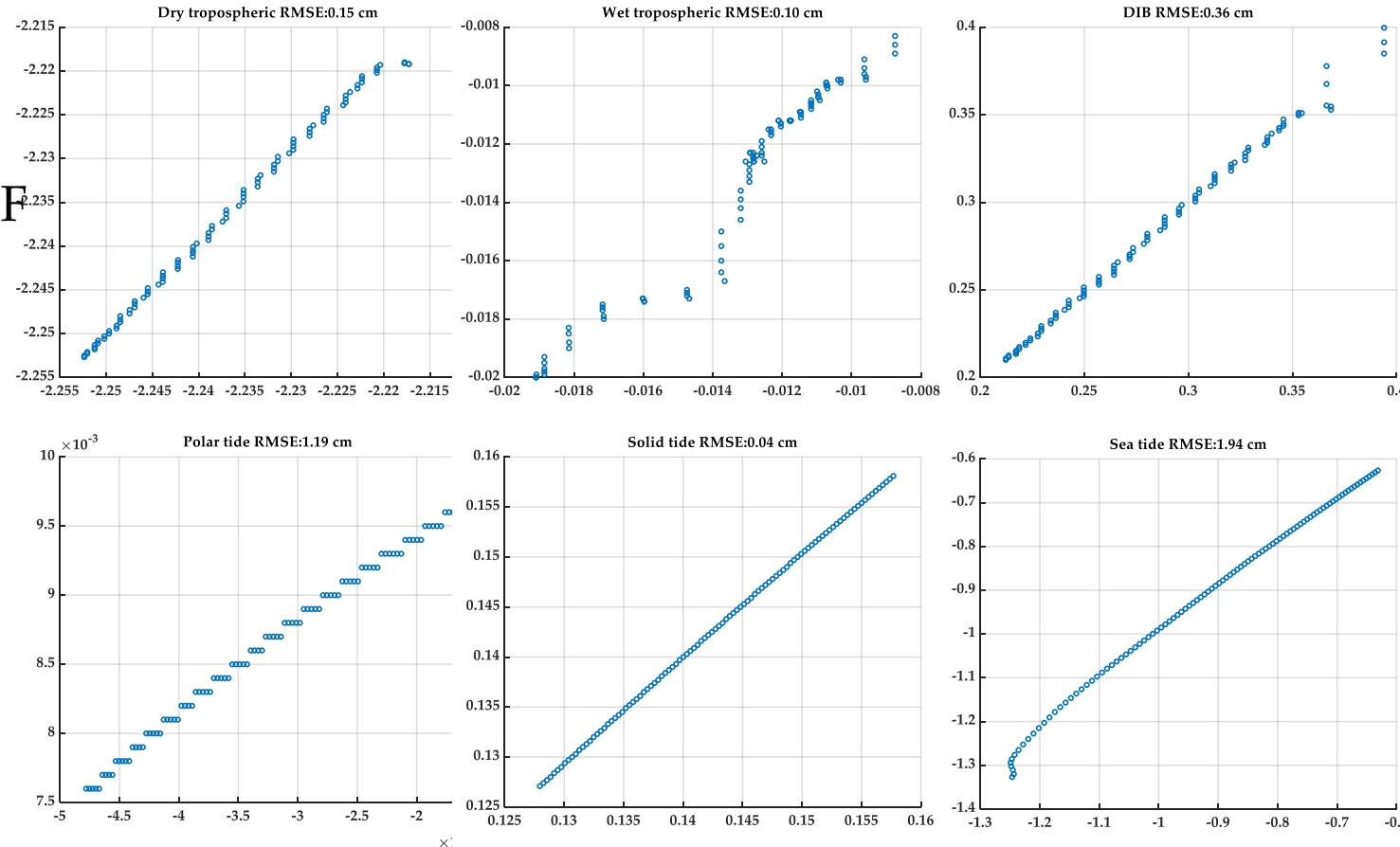
Polar Tide Correction: IERS

DIB Correction:

$$\rho_{bar} = -\frac{1}{\rho_w g} (p_a - \bar{p}_a) = -0.9948 (p_a - \bar{p}_a)$$

Solid Tide Correction:

Munk&Cartwright (1966)



the results after 3 years of activity
BF-1 Sea Surface Wind Retrieval by ML

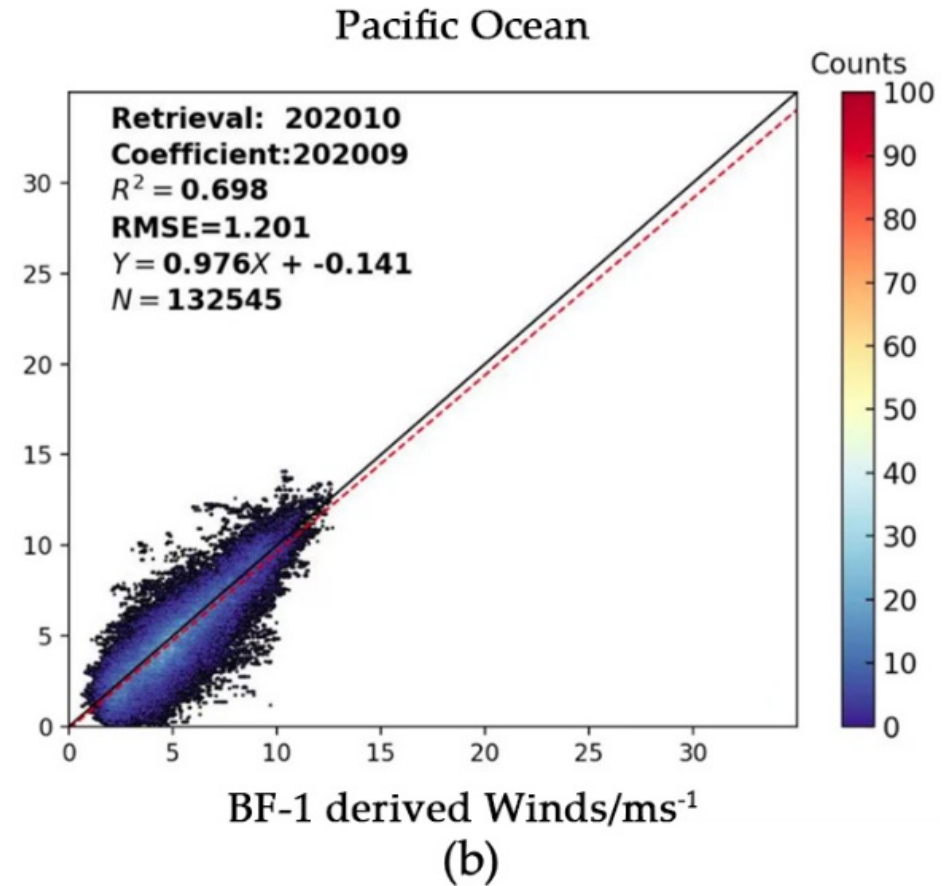
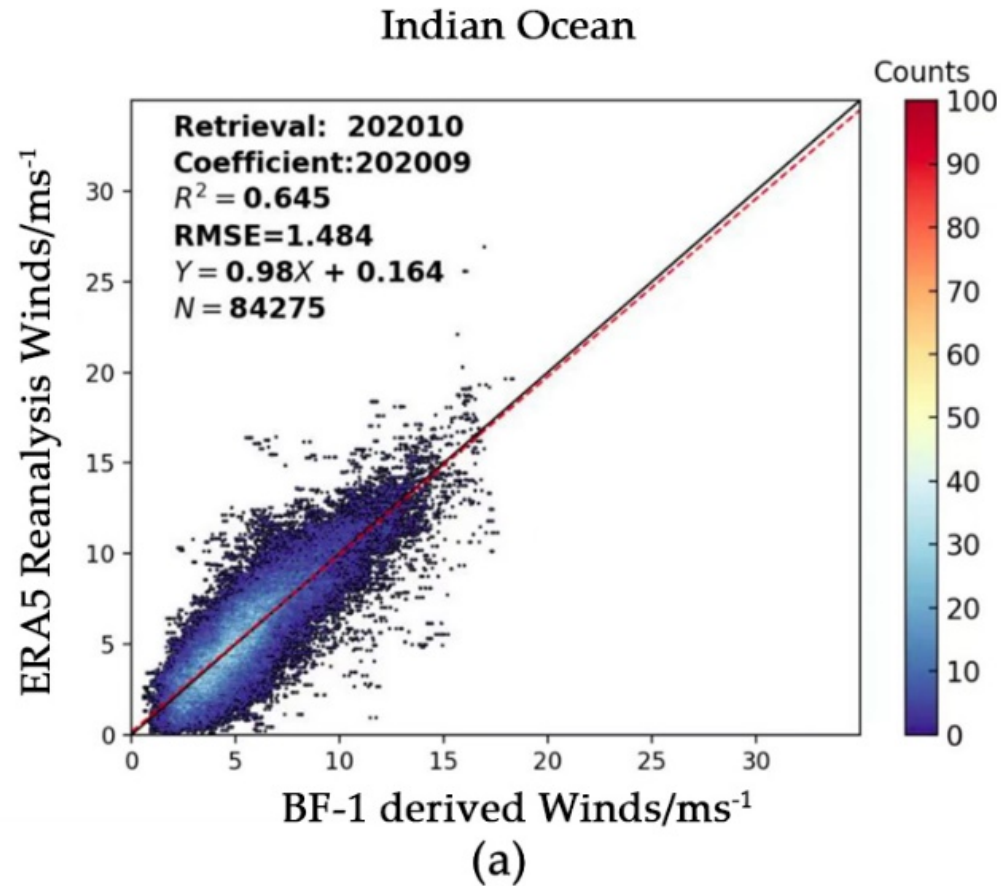
Sea Surface Winds by Machine Learning (ML)

High-performance computing cluster by CMA NSMC (BF-1 Client)

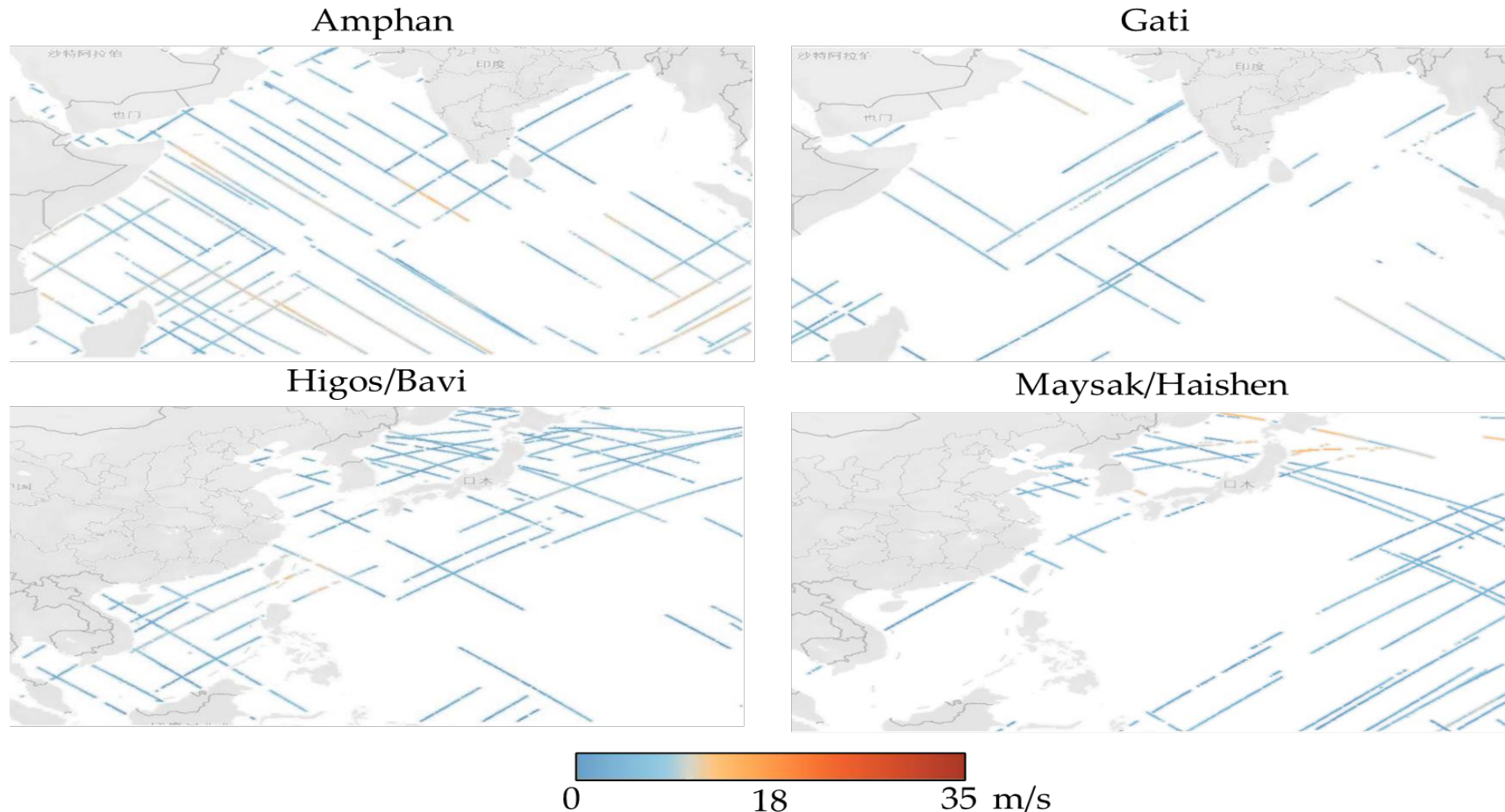
- open-source autoML framework named AutoGluon
- DDM observable is the NBRCS
- Data time: September and October, 2020
- Validation set: ECMWF ERA5 reanalysis

Input for Training	Wind speed retrieval	Result
NWP forecast windspeed	NWP forecast windspeed	Derived sea surface wind speed
Specular point latitude	Specular point latitude	
Specular point longitude	Specular point longitude	
Incident angle	Incident angle	
Receiver latitude	Receiver latitude	
Receiver longitude	Receiver longitude	
DDM SNR	DDM SNR	
NBRCS	NBRCS	
ERA5 reanalysis windspeed		

Sea Surface Winds by Machine Learning (ML) Results



Sea Surface Winds by Machine Learning (ML) Model Rerun for Typhoon/Hurricane



the results after 3 years of activity
BF-1 Sea Surface Wind under Hurricane Condition

Sea Surface Winds by GMF for Typhoon/Hurricane

Model function building with NOAA SFMR

- DDM observable is the NBRCS
- Wind range: 0.4 – 69.3 m/s
- Aligned pairs: 5,708
- QC: SNR>2
- R=0.78

Also follow the power function ($y=Axb+c$)

Using the average of different elevation bins

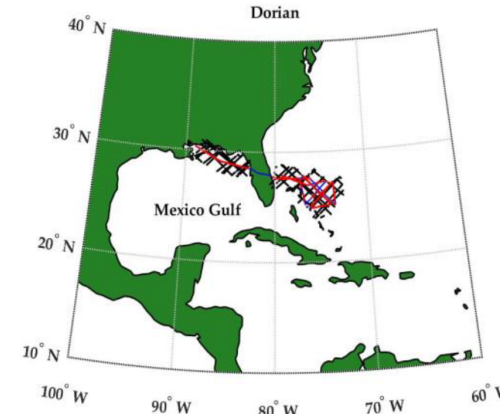
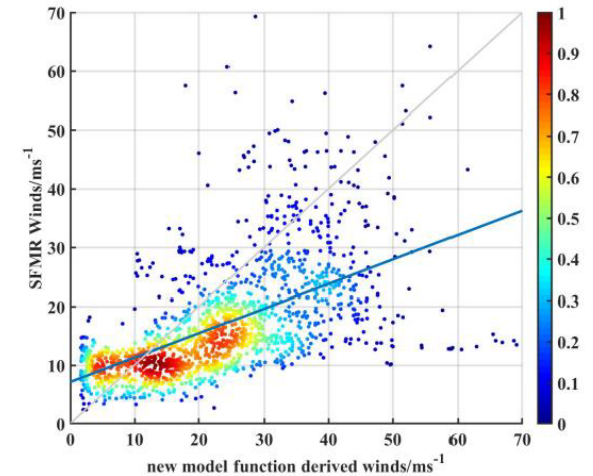
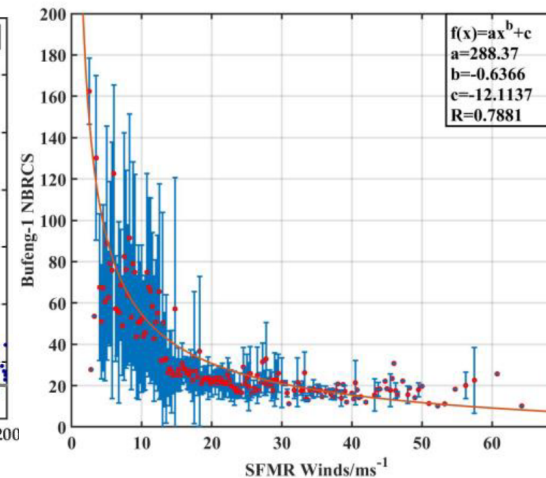
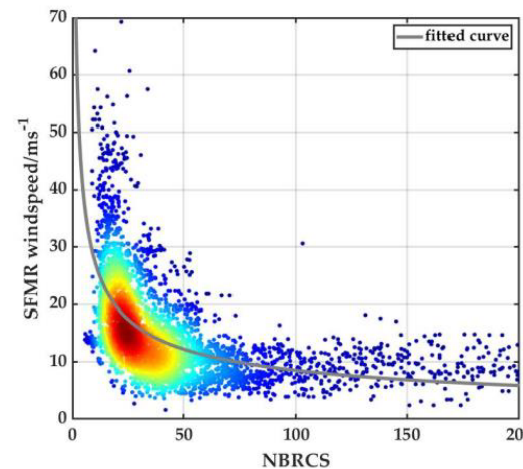


Table 1. NOAA Hurricane Season Data 2019

Name	Date	Volume
Barry	7/11-7/23	9
Dorian	8/26-9/6	35
Humberto	9/13-9/19	10
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Karen	9/22-9/26	7
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Lorenzo	9/28-9/29	2



the results after 3 years of activity
BF-1 Land Surface Soil Moisture

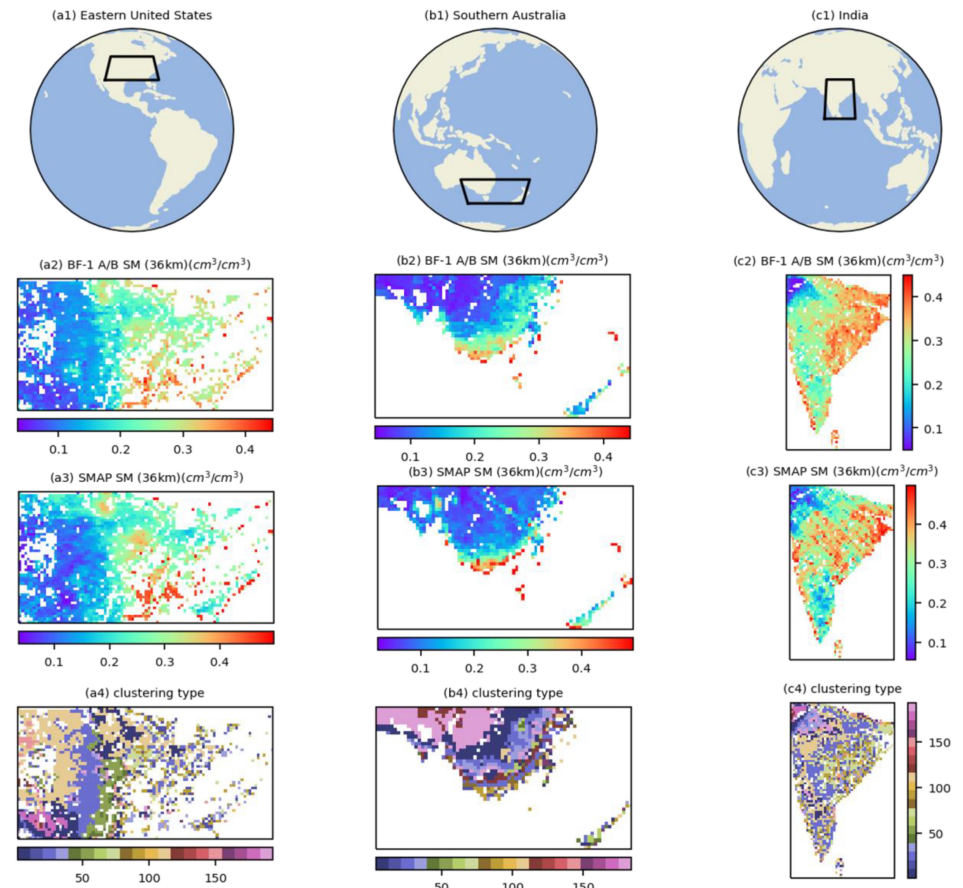
Inland Soil Moisture By Land Surface Clustering Algorithm(LSC)

The LSC algorithm is developed by PKU

- DDM observable is equivalent specular reflectivity
- Study area: Eastern United States, Southern Australia, and India
- Aligned data: ISMN sites, SMAP
- Performances:

SMAP vs BF-1: $ubRMSE=0.07 \text{ cm}^3/\text{cm}^3$, $R=0.82$

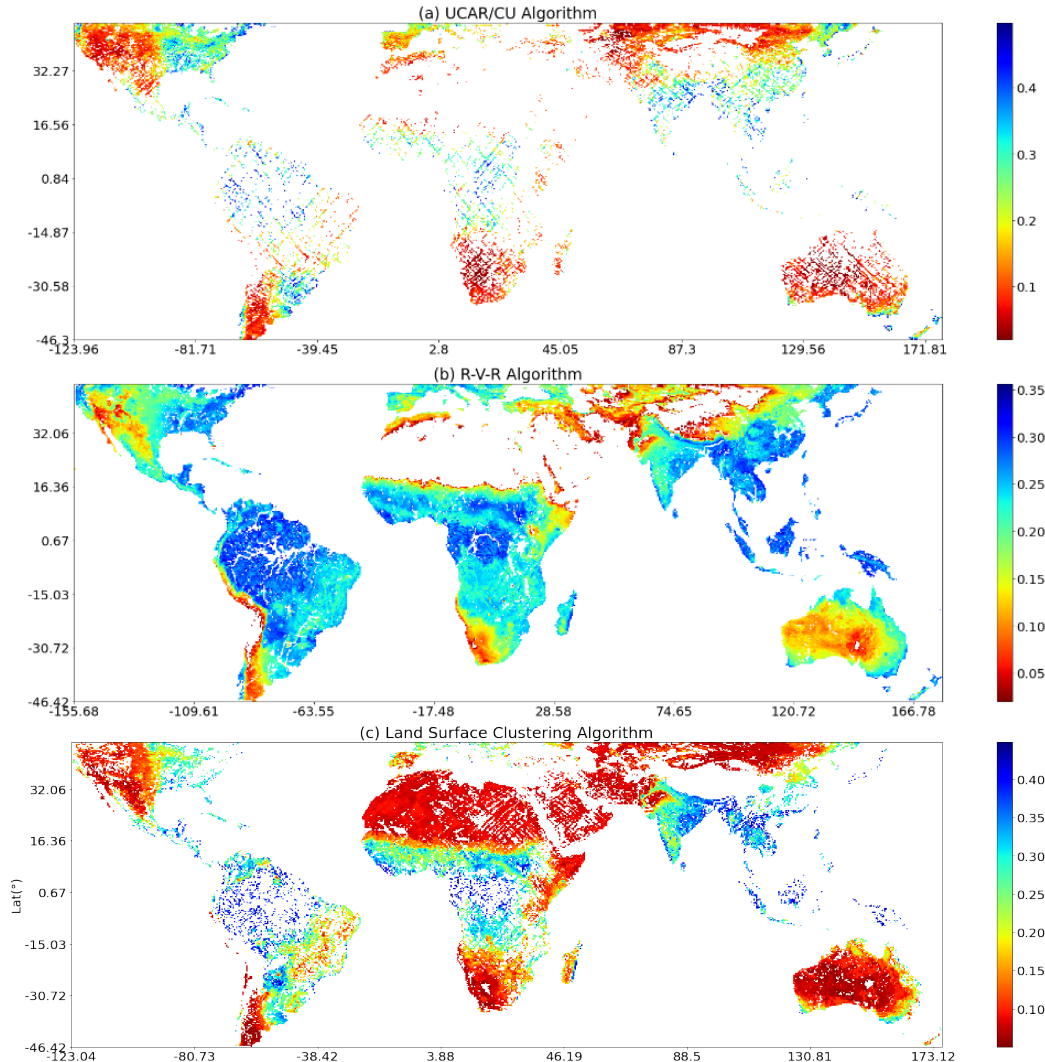
ISMN sites vs BF-1: $ubRMSE=0.036 \text{ cm}^3/\text{cm}^3$



Guo, Z., et al. (2022). "Soil moisture retrieval using BuFeng-1 A/B based on land surface clustering algorithm." *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing* **15**: 4680-4689.

Wan, W., et al. (2021). "Initial evaluation of the first chinese GNSS-R mission BuFeng-1 A/B for soil moisture estimation." *IEEE Geoscience and Remote Sensing Letters* **19**: 1-5.

Comparison of the performances of SM retrieval algorithms



UCAR/CU products
ubRMSE=0.057 cm³/cm³, R=0.86
Available SM area percentage(%) = 17.06

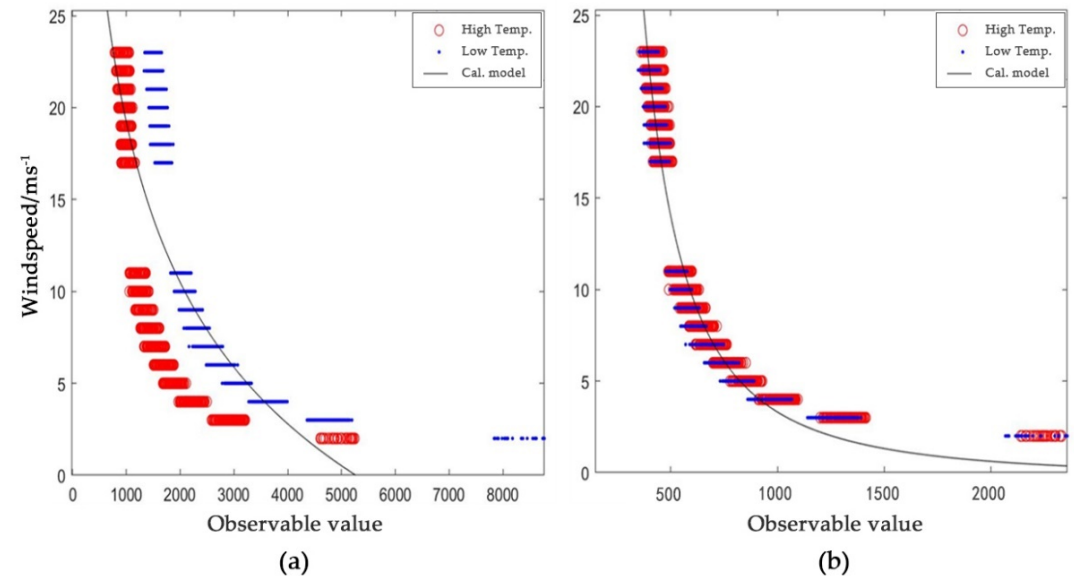
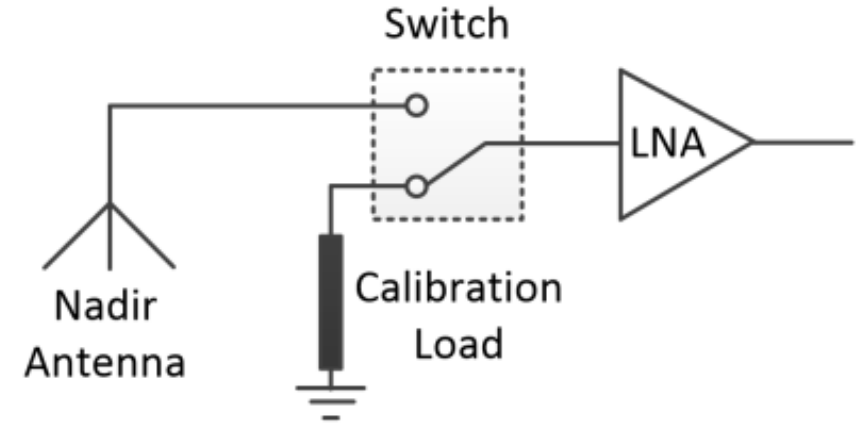
RVR(the reflectivity–vegetation–roughness)
ubRMSE=0.09 cm³/cm³, R=0.69
Available SM area percentage(%) = 47.38

PKU algorithm
ubRMSE=0.07 cm³/cm³, R=0.82
Available SM area percentage(%) = 35.63

the results after 3 years of activity
BF-1 Calibration and Validation

BF-1 Power Calibration

- power DDM collected by BF-1 GNSS-R instruments
- noise DDM output by blackbody payload every minute
- Low Noise Amplifier (LNA) instrument is easily affected by ambient temperatures.
- Calibration by a Power function



Schedule, Planning & Contribution

SCHEDULE & PLANNING:

- Phase 1: Preparation: Kick Off (KO) - KO+18
- Phase 2: Data Acquisition: KO - KO+42
- Phase 3: Calibration and validation: KO + 6 - KO + 48
- Midterm Theme Workshop 2022
- Phase 4: Showcases KO +32 - KO+48
- Phase 5: Integration KO +42 - KO+48
- Final Theme Workshop 2024
- Final project reporting

FUTURE CONTRIBUTIONS & PUBLICATION

- Ground observation for BDS EIRP and auto-correlation functions
- Preparing the data sharing to the GNSS-R community
- The instruments, high gain antennas and high rate receivers, are designed and developing for future ground validation experiments.
- The simulations of spaceborne GNSS-R bistatic waveforms and DDMs has been developed for ongoing and future space missions.
- Experiments of GNSS-SAR and airborne GNSS-R are expected in the next year.
- A review paper has been submitted to GSIS: A Review of The BuFeng-1 GNSS-R Mission: Calibration and Validation Results of Sea Surface and Land Surface

YOUNG SCIENTISTS CONTRIBUTIONS

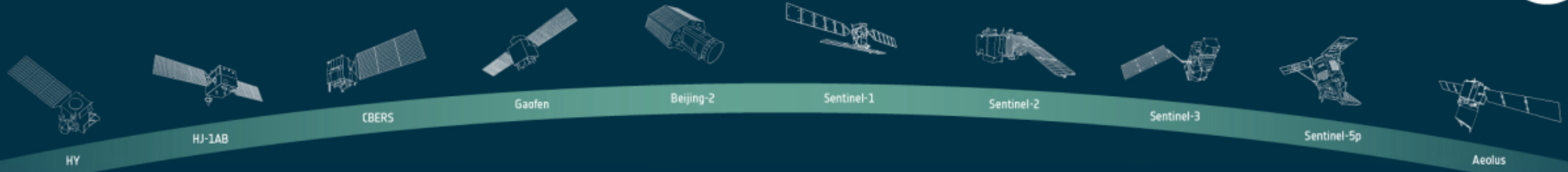
European Young scientists :

Dr. Yang Nan received the B.S. degree and M.S. degree in geomatics from Chang'an University, Xi'an, China, in 2012 and 2017 respectively. After Since 2019, He has studied at the Earth Observation Research Group, Institute of Space Sciences (ICE), Spanish National Research Council (CSIC), Institut d'Estudis Espacials de Catalunya (IEEC), Barcelona, Spain as a PhD students. He has been involved in Spaceborne GNSS-R retrieve wind field. Now he is a teacher of Tianjin University.

Chinese Young scientists :

Dr. Baojian Liu has received his Ph.D. degree in photogrammetry and remote sensing at Peking University. His research activity includes using spaceborne GNSS-R data and SMOS data to retrieve ocean salinity. Now he is a teacher of Beijing Forestry University.

Mr. Zhizhou Guo is pursuing his Ph.D. degree in photogrammetry and remote sensing at Peking University. His research activity includes using spaceborne GNSS-R data to retrieve soil moisture content.



Thanks for your attention

